

Using Sparse Matrix and Solver Routines from Intel MKL

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Outline

- Introduction
- Storage Formats
 - COO
 - CSR
 - CSC
- Sparse BLAS
- Sparse Solvers
- SCXX Library

What are Sparse Matrices

Definition

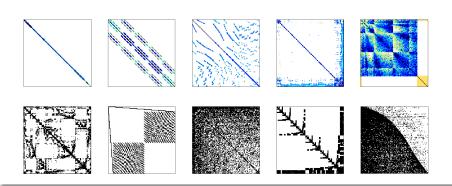
A matrix populated primarily by zeros.

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Examples



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Storage Formats

Reference

- The material in this section is taken from Intel MKL, Appendix A.
- To aid you in future reference of the manual I have used the manual's naming scheme and variable names.

Let's begin with an example sparse matrix

```
1 -1 * -3 * 

-2 5 * * * * 

* * 4 6 4 

-3 * 6 7 * 

* 8 * * -5
```

Let's begin with an example sparse matrix

```
    1 -1 * -3 * coordinate indices
    * * 4 6 4 coordinate indices
    * * 6 7 * coordinate indices
    Three vector representation
```

- Represent only non-zero values by their

Let's begin with an example sparse matrix

- Represent only non-zero values by their coordinate indices
- Three vector representation

```
values = ( 1 -1 -3 -2 5 4 6 4 -3 6 7 8 -5 ) rows = ( 0 0 1 1 2 2 2 2 3 4 0 2 3 1 4 ) columns = ( 0 1 3 0 1 2 3 4 0 2 3 1 4 )
```

Note: I have used 0-based indices: can also use 1-based indices

- Although COO improvement over dense matrices, can do better in terms of storage.
- There are duplicate values for the indices.

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Duplicate rows

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- There are duplicate values for the indices.

Duplicate rows

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rows = ( 0 0 0 1 1 2 2 2 3 3 3 4 4 )

columns = ( 0 1 3 0 1 2 3 4 0 2 3 1 4 )
```

Duplicate columns

As the name suggests, the rows are stored in compressed form.

- Stores only non-zero values
- Matrix indexing can be zero (C style) or one (Fortran style) based.
- Available in three or four vector formats. In Intel MKL
 - Four vector format is also called NIST Blas format
 - Three vector format is called CSR3

Let's see the difference between the two formats.

$$\begin{bmatrix} 1 & -1 & -3 \\ -2 & 5 & & \\ & 4 & 6 & 4 \\ -3 & 6 & 7 & \\ & 8 & & -5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & -3 \\ -2 & 5 & & \\ & 4 & 6 & 4 \\ -3 & & 6 & 7 \\ & & 8 & & -5 \end{bmatrix}$$

$$\begin{bmatrix}
1 & -1 & -3 \\
-2 & 5 & \\
& & 4 & 6 & 4 \\
\hline
-3 & & 6 & 7 & \\
& & 8 & & -5
\end{bmatrix}$$

$$\begin{bmatrix}
1 & -1 & -3 \\
-2 & 5 & \\
& & 4 & 6 & 4 \\
\hline
-3 & & 6 & 7 & \\
& & 8 & & -5
\end{bmatrix}$$

Three vector version

Number of Non-Zero Elements

Three vector version

Four vector version

```
values = \begin{pmatrix} 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ 1 & -1 & -3 & -2 & 5 & 4 & 6 & 4 & -3 & 6 & 7 & 8 & -5 \end{pmatrix} columns = \begin{pmatrix} 0 & 1 & 3 & 0 & 1 & 2 & 3 & 4 & 0 & 2 & 3 & 1 & 4 \end{pmatrix} pointerB = \begin{pmatrix} 0 & 3 & 5 & 8 & 11 & 1 \end{pmatrix} pointerE = \begin{pmatrix} 3 & 5 & 8 & 11 & 13 & 1 \end{pmatrix}
```

Three vector version

```
values = \begin{pmatrix} 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ \hline 1 & -1 & -3 & -2 & 5 & 4 & 6 & 4 & -3 & 6 & 7 & 8 & -5 \end{pmatrix}
columns = \begin{pmatrix} 0 & 1 & 3 & 0 & 1 & 2 & 3 & 4 & 0 & 2 & 3 & 1 & 4 \end{pmatrix}
rowlndex = \begin{pmatrix} 0 & 3 & 5 & 8 & 11 & 13 \end{pmatrix}
```

Four vector version

values =
$$\begin{pmatrix} 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ \hline 1 & -1 & -3 & -2 & 5 & 4 & 6 & 4 & -3 & 6 & 7 & 8 & -5 \end{pmatrix}$$

columns = $\begin{pmatrix} 0 & 1 & 3 & 0 & 1 & 2 & 3 & 4 & 0 & 2 & 3 & 1 & 4 \end{pmatrix}$

pointerB = $\begin{pmatrix} 0 & 3 & 5 & 8 & 11 & 1 \end{pmatrix}$

pointerE = $\begin{pmatrix} 3 & 5 & 8 & 11 & 13 \end{pmatrix}$

Note: The values and columns arrays are the same in both formats

Three vector version

```
values = \begin{pmatrix} 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ 1 & -1 & -3 & -2 & 5 & 4 & 6 & 4 & -3 & 6 & 7 & 8 & -5 \end{pmatrix} columns = \begin{pmatrix} 0 & 1 & 3 & 0 & 1 & 2 & 3 & 4 & 0 & 2 & 3 & 1 & 4 \end{pmatrix} rowlndex = \begin{pmatrix} 0 & 3 & 5 & 8 & 11 & 13 \end{pmatrix}
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values =
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Note: Connection between pointerB and pointerE.

- You will be fine just using the three vector format
- I will only use the three vector format in the rest of the talk
- What happens when a row is entirely empty??

```
-3
               -5
            6
```

```
values
        = ( -2 5 4 6 4 -3 6 7
             0 1 2 3 4 0 2 3 1
columns
rowIndex
               0
                 2 5 8
       = ( 1 -1 -3 4 6 4 -3 6
            0 1 3 2 3 4 0 2 3 1
columns
            0 3 3 6 9
rowIndex
            1 -1 -3 -2 5 4 6
values
              1 3
                   0 1 2 3 4
columns
rowIndex
              3 5 8 11 11 )
```

Compressed Sparse Column (CSC)

Similar to CSR, but instead the columns are stored in compressed form.

- Stores only non-zero values
- Matrix indexing can be zero (C style) or one (Fortran style) based.

$$\begin{bmatrix} 1 & -1 & * & -3 & * \\ -2 & 5 & * & * & * \\ * & * & 4 & 6 & 4 \\ -3 & * & 6 & 7 & * \\ * & 8 & * & * & -5 \end{bmatrix}$$
 • Represent only non-zero by their coordinate in the coordin

- Represent only non-zero values by their coordinate indices

This is the four-vector format

```
values = (1 -2 -3 -1 5 8 4 6 -3 6 7 4 -5)
rows = (0 1 3 0 1 4 2 3 0 2 3 1 4)
pointerB = (0 \ 3 \ 6 \ 8 \ 11)
pointerE = (3 \ 6 \ 8 \ 11 \ 13)
```

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Sparse BLAS

BLAS

Basic Linear Algebra Subroutines

Most (if not all) of you may be already familiar with BLAS routines operating on dense arrays. They come in three levels:

- BLAS Level 1 Vector-Vector Operations
- BLAS Level 2 Matrix-Vector Operations
- BLAS Level 3 Matrix-Matrix Operations

MKL provides an extension to BLAS for sparse matrices called Sparse BLAS

Sparse BLAS

BLAS

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- BLAS Level 1 Vector-Vector Operations
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Sparse Vectors

Before discussing Sparse BLAS Level 1, we need a brief digression into sparse-vectors.

Sparse Vectors

The Intel MKL uses the following terms to describe vectors for BLAS routines:

Compressed sparse vectors

In this form only non-zero elements and their indices are stored. I.e. there a total of two arrays are required to describe the sparse-vector - one containing the elements and the other containing the indices.

Full-storage vectors

This is just the usual dense form of the vector.

Sparse BLAS Level 1

Naming Conventions

If the Sparse BLAS routine is an extension of a regular BLAS routine then it's name is derived by appending an i at the end of the corresponding dense BLAS routine.

Examples

Dense BLAS	Sparse BLAS	Description
saxpy	saxpyi	Single-Precision scalar-vector product plus vector
ddot	ddoti	Double-Precision Dot product
sdot	sdoti	Single-Precision Dot product

Note: There are some dense BLAS Level 1 routines that will work with compressed-form array (with the parameter incx = 1), such as dcopy. See Manual.

Useful

- Level 2 and 3 routines are useful for building iterative solvers for large sparse systems.
- Such solvers are based on Reverse Communication Interface (RCI).

Terminology

In the next few slides the following terms will be used:

- Typical/Conventional interface Interface similar to that of NIST Sparse BLAS library.
- Simplified interface Essentially supports CSR3.

Naming Scheme

Each routine has a six- or eight-character base name prefixed by either mkl_ or mkl_cspblas_.

Typical Interface

The routines have the following template:

mkl_<character><data><operation>

Simplified Interface

The routines have the following template:

For one-based indexing :-

mkl_<character><data><mtype><operation>

For zero-based indexing :-

mkl_cspblas_<character><data><mtype><operation>

<character> can be:

- real single precision
- c complex single precision
- d real double precision
- z complex double precision

<character> can be:

- real single precision
- c complex single precision
- d real double precision
- z complex double precision

<data> can be:

coo coordinate format
csr CSR and variants

csc CSC and variants

dia diagonal format

sky skyline format

bsr block sparse row format

<character> can be:

- s real single precision
- c complex single precision
- d real double precision
- z complex double precision

<operation> can be:

mv matrix-vector product (Level 2)

mm matrix-matrix product (Level 3)

sv solve single triangular system (Level 2)

sm solve \triangle system with multiple RHS (Level 3)

<data> can be:

coo coordinate format

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<character> can be:

- real single precision
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<data> can be:

COO	coordinate format	
csr	CSR and variants	
CSC	CSC and variants	
dia	diagonal format	
sky	skyline format	
bsr	block sparse row format	

<operation> can be:

- mv matrix-vector product (Level 2)
- mm matrix-matrix product (Level 3)
 sv solve single triangular system
- (Level 2)
- sm solve \triangle system with multiple RHS (Level 3)

<mtype> can be:

- ge general matrix
- sy upper or lower △ of a symmetric matrix
- tr triangular matrix

Examples

Matrix-vector product of a sparse general matrix

	0-based	1-based
Simplified	mkl_cspblas_?csrgemv	mkl_?csrgemv
Typical	mkl_?csrmv	mkl_?csrmv

Note: Simplified form uses CSR3 and Typical form uses CSR4.

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Solver Solvers

Types

There are two types of solvers available in the MKL:

- Direct Solvers
- Iterative Solvers

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- Direct Solvers
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Only discuss the general operation of these routines.

Reference

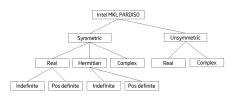
See Chapter 8 in the MKL.

PARDISO stands for PARallel Direct SOlver.

The Intel MKL PARDISO package is a high-performance, robust, memory efficient, and easy to use software package for solving large sparse linear systems of equations on shared memory multiprocessors. - MKL Manual

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Matrices that PARDISO can solve.

PARDISO solving process has multiple "phases". You have to call the same function more than once to process these phases.

The phases are:

- Phase 1: Fill-reduction analysis and symbolic factorization
- Phase 2: Numerical factorization
- Phase 3: Forward and backward solve and optional iterative refinement
- Phase 4: Memory release phase

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See manual for detailes. See code samples for usage.

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What is RCI?

A group of user-callable routines that are used in the step-by-step solving process.

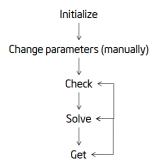
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What can RSS-ISS solve?

- Symmetric Positive Definite System Uses Conjugate Gradients (CG)
- Non-symmetric Indefinite System
 Uses Flexible Generalized Minimul Residual Solver (FGMRES)



DCT TCC Interface Doubles

RCI 155 Interface Routines			
Routine	Description		
dcg_init, dcgmrhs_init, dfgmres_init	Initializes the solver.		
dcg_check, dcgmrhs_check, dfgmres_check	Checks the consistency and correctness of the user defined data.		
dcg, dcgmrhs, dfgmres	Computes the approximate solution vector.		
dcg_get, dcgmrhs_get, dfgmres_get	Retrieves the number of the current iteration.		

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SCXX Library

Description

Stands for *Scientific CXX* is a templated linear algebra library that I have written over the past year that provides:

- Dense vectors
- 2 Dense matrices (2D, 3D and 4D)
- Sparse 2D Matrices
- Postscript plotting routines (useful for debugging)
- Computational grids
- 6 Solvers (coming soon)

The classes that implement the above structures provide:

- ① Operator overloading for: +, -, *, /, =, *=, +=, -=, », «, (), []
- Mathematical functions such as MATMUL, DOT, TRIPLE_PRODUCT, Mag()
- C++ exception handling
- Debugging support
- Sparse matrix routines

I want to talk briefly about the support for sparse matrices.

SCXX Sparse Module

The library provides the following sparse matrix classes: SMatrixSP_COO, SMatrixSP_CSR, SMatrixSP_CSC

These classes:

- Provide convenient single object handle for a sparse matrix.
- Pormat inter-conversion (via overloaded assignment operator =)
- Sparse Matrix-Dense Vector multiplication
- Neatly formatted output (via overloaded output operator «)
- Easy insertion of data (via function-call operator) void operator()(Double val, Int32 row, Int32 col) This manages the difficult task of generating the pointers array for the CSR and CSC formats.
- Easy accessing of data (via fucntion-call operator) Double operator()(Int32 row, Int32 col)
- Methods to retrieve internal pointers for use in external routines (such as those of Intel MKL)

THE END!